Manual of Brushless Motor Speed Controller

HK0001-SM006ENG-20130729 Page 1 of 3

Thanks for purchasing our Electronic Speed Controller (ESC). High power system for RC model is very dangerous, please read this manual carefully. In that we have no control over the correct use, installation, application, or maintenance of our products, no liability shall be assumed nor accepted for any damages, losses or costs resulting from the use of the product. Any claims arising from the operating, failure or malfunctioning etc. will be denied. We assume no liability for personal injury, property damage or consequential damages resulting from our product or our workmanship. As far as is legally permitted, the obligation to compensation is limited to the invoice amount of the affected product.

Features

- 1. 4 speed controllers in1board, only 1 pair of battery wire is needed.
- 2. Powerful switch mode built-in BEC (the BEC voltage outputs from the S3 connector).
- 3. Multiple protection features: Low voltage cut-off protection / over-heat protection / throttle signal loss protection.
- 4. The throttle range of each ESC can be calibrated to be suitable for different multi-rotor flying control systems / transmitters.
- Maximum speed: 210000 RPM (2 poles motor), 70000 RPM (6 poles motor), 35000 RPM (12 poles motor).





Specification

| Model | Cont. | Burst Current | Mode Output | BEC Output Capability | | Battery Cell | | Weight | Size | | |
|-----------------------------|----------------|------------------|-------------|-----------------------|----------|--------------|----------|--------|------------|------|----------|
| 自由的原理的原理的自由的原理的 | Current (>10s) | (>10s) | | Output | 2S Lipo | 3S Lipo | 4S Lipo | Lipo | NiMH | | L*W*H |
| QBrain 4*20A Quadcopter ESC | 20A*4 | 25A*4 | Switch mode | 5V@3A | 5 servos | 5 servos | 4 servos | 2-45 | 5-12 cells | 112g | 70*62*11 |
| QBrain 4*25A Quadcopter ESC | 25A*4 | 30A*4 | Switch mode | 5V@3A | 5 servos | 5 servos | 4 servos | 2-4S · | 5-12 cells | 112g | 70*62*11 |

Programmable Items (The option written in bold font is the default setting)

- 1. Brake: Disabled / Enabled
- 2. Battery Type: Lipo / NiMH
- 3. Low Voltage Protection Mode (Cut-Off Mode): Soft Cut-Off (Gradually reduce the output) /Cut-Off (Immediately stop the output)
- 4. Low Voltage Protection Threshold (Cut-Off Threshold): Low / Medium / High
 - a) For lithium battery, the battery cell amount is calculated automatically. Low / medium / high cutoff voltage for each cell is: 2.85V/3.15V/3.3V. For example: For a 3S Lipo battery, when "Medium" cutoff threshold is set, the cut-off voltage will be: 3.15*2=9.45V
 - b) For NiMH battery, low / medium / high cutoff voltages are 0% / 50% / 65% of the startup voltage (i.e. the initial voltage of battery pack), and 0% means the low voltage cut-off function is disabled. For example: For a 6 cells NiMH battery, fully charged voltage is 1.44*6=8.64V, when "Medium" cut-off threshold is set, the cut-off voltage will be 8.64*50%=4.32V.

Warning! In order to protect the expensive multi-rotor, the default settings (i.e. Battery Type = "NiMH" and Cut-Off Threshold = "Low") don't take any protection even if the Lipo battery is over discharged. If you do need to activate the battery protection function please change the default settings.

5. Startup Mode: **Normal** /Soft /Super-Soft (300ms / 1.5s / 3s)

The initial acceleration of the Soft and Super-Soft modes are slower than the Normal mode, it takes 1.5 second for Soft startup or 3 seconds for Super-Soft startup from initial throttle advance to full throttle. If the throttle is completely closed (throttle stick moved to bottom position) and opened again (throttle stick moved to top position) within 3 seconds after the first startup, the re-startup will be temporarily changed to normal mode to get rid of the chance of a crash caused by slow throttle response. This special design is suitable for aerobatic flight when quick throttle response is needed.

6. Timing: Low / Medium / High,(3.75°/ 15°/ 26.25°)

Usually, the default timing is suitable for most motors. To get higher speed, High timing can be chosen.

Begin To Use Your New ESC

Because different transmitters / flying control systems have different throttle ranges, please calibrate the throttle range for each speed controller before flying.

The Throttle Signal HUB is recommended for calibrating the throttle ranges for 4 speed controllers simultaneously instead of one by one.

Throttle range setting:

Note: The throttle range of each speed controller in the Quattro should be set separately. When the Quattro is installed in a multi-rotor, you should set the throttle range of each ESC via the flying control system.

| 5 | wit | ch | on | the |
|---|-----|-----|------|-------|
| t | rar | ISI | nit | ter, |
| n | nov | е | thre | ottle |
| s | tic | k | to | the |
| t | op | p | osi | tion |

Connect battery pack to the ESC, and wait for about 2 seconds

The "Beep-Beep-" tone should be emitted, means the top point of throttle range has been confirmed

Move throttle stick to the bottom position, several "beep-" tones should be emitted to present the amount of battery cells

A long "Beep-" tone should be emitted, means the lowest point of throttle range has been correctly confirmed

Manual of Brushless Motor Speed Controller

Normal startup procedure:

Move throttle stick to bottom position and then switch on transmitter Connect battery pack to ESC, special tone like " 123" means power supply is OK Several "beep-" tones should be emitted to present the amount of lithium battery cells When self-test is finished, a long "beep----" tone should be emitted

Move throttle stick upwards to go flying

HK0001-SM006ENG-20130729 Page 2 of 3

Protection Function

- Start up failure protection: If the motor failed to start within 2 seconds of throttle application, the ESC would cut-off the output power. In such a case, the throttle stick MUST be moved to the bottom position again to restart the motor. (Such a situation happens in the following cases: The connection between ESC and motor is not reliable, the propeller or the motor is blocked, etc.)
- 2. Over-heat protection: When the temperature of the ESC is higher than 110 Celsius degrees, the ESC will reduce the output power.
- Throttle signal loss protection: The ESC will reduce the output power if the throttle signal is lost for 1 second, further loss for 2 seconds will cause the output to be cut-off completely.

[Accessory: Throttle Hub]

Applications

- Use this throttle Hub to calibrate the throttle range for the Quattro ESC (The Quattro is an equipment in quadcopter, usually it has 4
 ESCs in 1 board):
- 2. Use this throttle Hub as throttle signal distributor for several speed controllers (1 ESC to 4 ESCs).

Operation

- 1. To calibrate the throttle range for the Quattro ESC:
 - a) Plug the throttle signal wires of 4 ESCs (S1 to S4) into Port #1 to Port #4 of the throttle Hub.
 - Attention! In the following picture, the pins at the symbol "S" line are the paths of throttle signals transmission.
 - b) Plug the lead at right side into the throttle channel of receiver or fly-control system.
 - Connect battery to the Quattro ESC.
 - d) Calibrate throttle range of the 4 ESCs in the Quattro simultaneously.
- 2. To distribute throttle signal to several ESCs
 - Generally, in case of throttle signal distribution, only one ESC has its built-in BEC enabled (or reserved), the BECs in other ESCs must be disabled (That is, cut the red wires in the Rx cables)
 - b) Plug the throttle signal wires of 4 ESCs into Port #1 to Port #4 of the throttle Hub.
 - Attention! In the following picture, the pins at the symbol "S" line are the paths of throttle signals transmission.
 - e) Plug the lead at right side into the throttle channel of receiver.



Trouble Shooting

| Markin Remarks and Louis Charles and Remarks and | Possible Reason | ACTION ACTION |
|--|---|---|
| After power on, motor doesn't work, no sound is emitted | The connection between battery pack and ESC is not correct | Check the power connection. Replace the connector. |
| After power on, motor doesn't work, such an alert tone is emitted: "beep-beep-, beep-beep-" (Every "beep-beep-" has a time interval of about 1 second) | Input voltage is abnormal, too high or too low. | Check the voltage of battery pack |
| After power on, motor doesn't work, such an alert tone is emitted: "beep-, beep-, beep-" (Every "beep-" has a time interval of about 2 seconds) | Throttle signal is abnormal. | Check the receiver / transmitter / flying controller Check the cable of throttle channel |
| After power on, motor doesn't work, such an alert tone is emitted: "beep-, beep-, beep-" (Every "beep-" has a time interval of about 0.25 second) | The throttle stick is not in the bottom (lowest) position | Move the throttle stick to bottom position |
| After power on, motor doesn't work, a special tone " 56712" is emitted after 2 beep tone (beep-beep-) | The Direction of throttle channel is reversed, so the ESC enters the program mode | Set the direction of throttle channel correctly |
| The motor runs in the opposite direction | The connection between ESC and the motor need to be changed. | Swap any two wire connections between ESC and motor |
| | | |

Note: Please make sure the throttle volume is set to 0 when the throttle stick is moved to the bottom position and 100% at the top position

- Enter program mode Select programmable items
- Select options (Programmable value)
- Exit program mod

1. Enter program mode

- Switch on transmitter, move throttle stick to top position, connect the battery pack to ESC
- 2) Wait for 2 seconds, the motor should emit special tone like "beep-beep-"
- V ≯ it for another 5 seconds, special tone like " 56712" should be emitted, which means program mode is entered

2. Select programmable items:

After entering program mode, you will hear 8 tones in a loop with the following sequence. If you move the throttle stick to bottom within 3 seconds after one kind of tones, this item will be selected.

| ١. | "beep" | brake | (1 short tone) |
|----|--------------|--------------|----------------|
| 2. | "beep-beep-" | battery type | (2 short tone) |

- (3 short tone) cutoff mode "beep-beep-beep-"
- "beep-beep-beep-" cutoff threshold (4 short tone)
- startup mode (1 long tone)
- timing (1 long 1 short) "beep----beep-" 6. set all to default (1 long 2 short)
- "beep----beep-beep-" (2 long tone) exit "beep----beep----"

 $\odot\Box\odot$

Note: 1 long "beep----" = 5 short "beep-"

@0Q $\odot\Box \odot$ ©¤Ģ

3. Select option (Programmable value):

You will hear several tones in loop. Set the value matching to a tone by moving throttle stick to top when you hear the tone, then a special tone " 1515" emits, means the value is set and saved. (Keeping the throttle stick at top, you will go back to Step 2 and you can select other items; or moving the stick to bottom within 2 seconds will exit program mode directly)

⊙□**₫**

| Tones Items | "beep-" 1 short tone | "beep-beep-" 2 short tones | "beep-beep-beep" 3 short tones | | |
|------------------|----------------------|----------------------------|--------------------------------|--|--|
| Brake | Off * | On | | | |
| Battery type | Lipo 🏶 | NiMH | | | |
| Cutoff mode | Soft-Cut # | Cut-Off | | | |
| Cutoff threshold | Low # | Medium | High | | |
| Start mode | Normal # | Soft | Super soft | | |
| Timing | Low | Medium # | High | | |

4. Exit program mode

There are 2 ways to exit program mode:

- 1. In step 3, after special tone " i5i5", please move throttle stick to the bottom position within 2 seconds.
- 2. In step 2, after tone "beep----"(ie. The item #8), move throttle stick to bottom within 3 seconds.

- NOTE:

 1. Each speed controller in the Quattro must be programmed separately.

 2. Please make sure the settings for each speed controller in the Quattro are same.